AMENDMENTS TO THE SPECIFICATION

Please replace Paragraph [0008] with the following paragraph rewritten in amendment format:

[0008] Figure 1 is ~~an~~ a partial exploded perspective view of a reclining chair incorporating the actuation mechanism of the present invention;

Please replace Paragraph [0020] with the following paragraph rewritten in amendment format:

[0020] A drive motor 32 is operably coupled to drive rod 22 to provide a motor-driven drive rod. As presently preferred, drive rod 22 is a one-piece element which extends through the gear set of drive motor 32 at the rearward portion of the drive motor 32. One ~~skill~~ skilled in the art will recognize that the drive motor which is shown within the actuation mechanism 14 may be located at ~~other~~ another position. In this regard, the drive motor 32 may be located outboard of the location shown. For example, the drive motor 32 may be located within a cavity of one of the side frame assemblies. The front portion of the drive motor 32 is supported by motor brace 34 extending downwardly from front support shaft 24. The drive mechanism further includes motor control circuitry (not shown) to selectively operate the drive motor through the range of motion without overload thereof. A presently preferred drive motor is the subject of United States Application No. 10/196,851, the disclosure of which is expressly incorporated by reference herein.

Please replace Paragraph [0022] with the following paragraph rewritten in amendment format:

[0022] The support bracket 38 has a hook portion 42 which extends through a slot 44 formed in the rear frame rail member 18 and captures the upper edge 46 thereof. Support bracket 38 is cantilevered from the chair frame 12 and extends downwardly and forwardly from the rear frame rail member 18 and terminates at end 46 which receives one end of spring member 40. The bracket 38 is able to support the spring of the spring member 40 without fasteners securing it to the chair frame assembly ~~14~~12. As such, the position of the support bracket 38 relative to the rear frame rail ~~20 maybe~~ 18 may be readily adjusted. A stud 50 (as shown in Figure 4) extends from pantograph linkage 30 and receives the other end of spring member 40. Return spring mechanism 36 biases the follower link 64 rearwardly in a counterclockwise direction to urge the pantograph linkage 30 towards the retracted position.

Please replace Paragraph [0023] with the following paragraph rewritten in amendment format:

[0023] Front frame member assembly 20 is a multi-piece assembly including front frame board 52 and a pair of front frame brackets 54 extending from opposite lateral ends of front frame board 52. Spacer link 56 is interconnected between drive rod 22, front support shaft 24 and frame board 52 to further integrate actuation mechanism ~~16~~ 14 with chair frame assembly ~~14~~12.

Please replace Paragraph [0025] with the following paragraph rewritten in amendment format:

[0025] In this way, the front brace 60 and rear brace 58 may be separated to facilitate field service and replacement of the actuation mechanism without further requiring disassembly of the chair frame assembly 12. Specifically, the drive rod 22 along with the drive motor 32 may be uncoupled and removed from the chair frame ~~14~~ assembly 12 without requiring excessive disassembly of the unit. Specifically, the spring members 40 are uncoupled from the follower link 64. Next, the various links – leg rest swing arm 74, follower link 64 and rear brace 58 – are uncoupled from the drive rod 22. Then, the rear brace is uncoupled from the front brace 60 by removing fasteners 62. Lastly, the motor mount 34 is uncoupled from the drive motor 32. At this point the drive rod 22 and drive motor 32 may be moved laterally relative to the remaining component of the chair and removed therefrom. Once the drive motor 32 has been serviced or replaced, the drive rod 22 and drive motor may be re-installed using the reverse sequence described above.

Please replace Paragraph [0028] with the following paragraph rewritten in amendment format:

[0028] Pantograph linkage 30 further includes support link 78 pivotally connected at pivot 80 to connection link 82, which is pivotally connected at pivot 84 with front board link 86 which is in turn pivotally connected at pivot 88 with leg rest bracket 90. Similarly, leg rest swing arm 74 is pivotally connected at pivot 92 to rear board link 94 which is, in turn, pivotally connected at pivot 96 to leg rest bracket 90. Leg rest swing arm

74 is pivotally coupled at intermediate pivot 98 with support link 78. Rear board link 94 is pivotally coupled at intermediate pivot 100 with connection link 82. Follower link 64 is pivotally coupled at pivot 102 with support link 78. In this manner, pantograph linkage 30 provides means for articulating the leg rest assembly between a retracted position as illustrated in Figure 5 to a fully extended position as illustrated in Figure 6.

Please replace Paragraph [0029] with the following paragraph rewritten in amendment format:

[0029] Drive link 104 is supported on and rotates with drive rod 22. Specifically, drive link 104 receives drive rod 22 and is rotatably coupled thereto. Nylon washer 106 is interposed between drive link 104 and bushing 70. Transverse flange 108 extends laterally outwardly from drive link 104 and is adapted to engage the rearward edge 110 of follower link 64. Accordingly, selective rotation of drive rod 22 in a counter-clockwise direction (as shown in Figs. 5-7) rotates drive link 104 causing transverse flange 108 to engage rear edge 110 of follower link 64, thereby rotating follower link 64 in a counter-clockwise direction. Follower link 64 which acts through pivot 102 moves support link 78. Such movement of support link 78 causes leg rest swing arm 74 to rotate about front support shaft 24 moving rear board link 94 outwardly and upwardly. In addition, the pivotally coupling of support link ~~98~~ 78 with connection link 82 and front board link 86 results in coordinated upward and outward movement of front board link 86. Extension of left and right hand pantograph linkages 30 is simultaneous to position the leg rest assembly from a stored or retracted position shown in Figure 5 to an extended or protracted position as shown in Figure 6.